Table of Content

Mechanisms of hygromorphic actuation: from analysis to tuning of biomimetic actuators for adaptive facades 1
Eleonora Galli, Mohamed Abdelrasoul, Jürgen Rühe
(University of Freiburg, Germany)

An AlN piezoelectric thermomagnetic generator for waste heat recovery 4
Maxim Wischnewski, Erik Mackensen, Dirk Meyners, Manfred Kohl
Karlsuhe Institute of Technology (KIT), Germany
Christian-Albrechts-Universität (CAU), Kiel, Germany

Piezoelectric Fine Steering Mirrors and electronics for Optical Inter-Satellite Links 10
Xavier De Lépine, Jocelyn Rebufa, David Ferris, Aurore Loubet, Frank Claeyssen, Sylvain Chardon, Arnaud Gilson, Thomas Maillard, Pascal Mexe, Francis Bortolaso
CEDRAT TECHNOLOGIES S.A.S, France
MICROTEC S.A.S, France

A miniature-scale thermomagnetic actuator driven by low-grade heat 18
Athira Kattiparambil Sivaprasad, Joel Joseph, Amir-Abbas Haghighirad, Manfred Kohl, Jingyuan Xu
Institute of Microstructure Technology (IMT), Karlsruhe Institute of Technology (KIT), Germany
Institute for Quantum Materials and Technologies (IQMT), Karlsruhe Institute of Technology (KIT), Germany

Magnetic Fast Steering Mirrors for Tracking and Optical Communication for Defense and Aerospace Industries 22
Xavier De Lépine, Timotéo Payre, Clément Joseph Galteau, Nabil Bencheikh, Patrick Meneroud, Florian Bonnet, Hugo Grardel, Pierre Personnat, Clément Cote, Guillaume Mansuy, Arnaud Gilson, Frank Claeyssen
Cedrat Technologies, France

Shape Memory Alloy drives for micro-electronical actuator systems 28
Andreas Erben, Daniel Hoffmann, Kenny Pagel,Sven Spieth, Alexander Jähnigen, Welf-Guntram Drossel, Alfons Dehé
Fraunhofer Institute for Machine Tools and Forming Technology IWU, Dresden, Germany
Hahn-Schickard Gesellschaft, Villingen-Schwenningen, Germany

Tailoring the spatial thickness distribution of a membrane using 3D printing for enhanced operation as a dielectric elastomer actuator 30
Andreas Hubracht, Bingzhi Wanga, Chen Jiaob, Ashwani Sharan Tripathib, Uwe Marschnerb, Andreas Richterb, E.-F., Markus Vorrath, Jürgen Maas
Mechatronic Systems Lab, Technische Universität Berlin,
Institute of Semiconductors and Microsystems, Technische Universität Dresden

Robust and Efficient Finite Element Modeling of an Electrostatic Microactuator Relying on the Pull-In Effect 36
Arwed Schütz, Dwarakesh Sudhahar, Martin Hoffmann,, Tamara Bechtold
Jade University of Applied Sciences, Wilhelmshaven, Germany
Microsystems Technology, Ruhr University Bochum, Germany

Electrostatic MEMS actuator for controlled Quasi-Static spherical Rotation 41
Dwarakesh Sudhahar, Arwed Schütz, Martin Hoffmann, Tamara Bechtold
Microsystems Technology, Ruhr University Bochum, Germany
Jade University of Applied Sciences, Wilhelmshaven, Germany

Highly Conductive Metallic Thin Films on Flexible Substrates 44
Benjamin R. Zemlin, Jonas Hubertus, Dirk Göttel, Alberto Priuli, Saveria Addario, Gianluca Rizzelo, Stefan Seelecke, Günter Schultes, John Heppe
University of Applied Sciences of Saarland, Saarbruecken, Germany
Saarland University, Saarbruecken, Germany

Towards scaling Cooperative Dielectric Elastomer Actuator Systems 47
Alberto Priuli, Saverio Addario, Benjamin Zemlin, John Heppe, Gianluca Rizzello
Saarland University, Department of Systems Engineering, Saarbrücken, Germany
University of Applied Sciences, Department of Sensors and Thin Films, Saarbrücken, Germany.

Response Surface Modeling and Multi-Response Optimization of PVDF/BaTiO3/CNT Films for Flexible Actuator Applications 51
Ahmed Attaoui, Ayda Bouhamed,Chokri Bouraoui, Olfa Kanoun
Professorship of Measurement and Sensor Technology (MST), Chemnitz University of Technology, Chemnitz, Germany Laboratory of Mechanics of Sousse (LMS), National Engineering School of Sousse (ENISo), University of Sousse, Technopole de Sousse, Sousse, Tunisia Faculty of Sciences of Gafsa (FSGF), University of Gafsa, Gafsa, Tunisia Laboratory of Electromechanical Systems (LASEM), National Engineering School of Sfax, University of Sfax, Sfax, Tunisia

Energy efficient electro-mechanical wing ice protection system for future aircrafts 63
Denis Becker, Thorsten Koch, Christopher Davies, Valerian Palanque, Matthias Schmidt, Valentin Mees, Michael Matthias
Fraunhofer LBF, Darmstadt, Germany
Parker Meggitt, Shepshed, Loughborough, United Kingdom
Airbus, Toulouse, France

Giving voice to flat plastic panels with piezoceramic actuators: vibrational analyses with feedback interferometry 65
Elisabetta Bodo, Carlo Anelli, Valentina Bello, Sabina Merlo
Eindhoven University of Technology, The Netherlands
University of Pavia, Italy

High-resolution rotating piezo motors for LISA large interferometer space antenna 67
Nicolas Bourgeot, Jocelyn Rebufa, Alexis Gierczak, Clément Cote, Olivia Stadler, François Barillot, Frank Claeyssen
(CEDRAT TECHNOLOGIES S.A.S, France)

Improving the reliability of piezoelectric actuators and motors subjected to significant self-heating and several billion actuation cycles or severe environments 73
Nicolas Bourgeot, Frank Claeyssen, Boris Laluc, Rasmus Lou-Møller, François Barrot, Iman Mehdipour, Yves Ruffieux, Guillaume Mansuy
CEDRAT TECHNOLOGIES S.A.S, France
CTS Corporation, Denmark
CSEM, Switzerland

Adaptive surface actuation via magnetoactive elastomer membranes 79
Ina Bregu, Jürgen Maas
(TU Berlin, Germany)

Electrostatically Actuated Liquid Lenses for an Anamorphotic Zoom 85
Debatri Das, Martin Hoffmann
(Microsystems Technology, Ruhr University Bochum, Germany)

Lead free 4-layered piezoelectric motor 90
Bülent Delibas, Burhanettin Koc
Physik Instrumente GmbH & Co. KG, Germany

Electromagnetic characterization of Magnetorheological Dampers Gabriel Dias Mendes 94
Cracow, *University of Technology, Poland*

Piezo actuated jet for stealth aircraft applications 98
David Ferris, Guillaume Mansuy, Boris Laluc, Jan Rohac
CEDRAT TECHNOLOGIES S.A.S, France
ESC Defence, Czech Republic

Soft robotic artificial muscles for end-stage heart failure management 103
Javad Foroughi, Arjang Ruhparwar
School of Mechanical and Manufacturing Engineering, University of New South Wales, Sydney, Australia; Department of Cardiothoracic Transplantation and Vascular Surgery Hannover Medical School, Germany

Antagonistic bistable actuator based on shape memory alloy beams 105
Yasmina Frey, Zeliha Arabul, Ulrike Wallrabe
(University of Freiburg, Germany)

Soft and monolithic variable Stiffness Clutches to enhance Serial Elastic Actuators 108
Johannes Frey, Mohsen Jafarpour, Hugo Oliveira, Edoardo Milana
Department of Microsystems Engineering - IMTEK, Cluster of Excellence livMatS, University of Freiburg, Germany

Metamaterial for a localized simulated button-click 112
Mondher Ouari, Frédéric Giraud, Charles Croënne, Jean-Luc Bruyelle, Christophe.giraud-Audine
UMR - IEMN, Univ. Polytec hnique Hauts-de-France, CNRS, Univ. Lille, Valenciennes, France
Univ. Lille, Arts et Metiers Institute of Technology, Centrale Lille, Junia, France

Assembly-oriented redesign of a shape memory alloy driven bistable gripper 114
Tom Gorges, Fabian Adler, Sarah Zimmer, Sophie Nalbach, Paul Motzki
Depart. Smart Material Systems, ZeMA – Center for Mechatronics and Automation Technology, Saarbruecken, Germany
Depart. Systems Engineering, Saarland University, Saarbruecken, Germany
Depart. Assembly Systems, ZeMA – Center for Mechatronics and Automation Technology, Saarbruecken, Germany

Multilayered electrohydraulic soft actuators for safe-to-touch wearables and underwater systems 119
Chinmay Gupta, Krishnaprasad Rajagopalan, Gaurav Khandelwal, Ajay Giri Prakash Kottapalli
Department of Bioinspired MEMS and Biomedical Devices (BMBD), Engineering and Technology Institute (ENTEG), University of Groningen, Netherlands
Department of Engineering Science, University of Oxford, United Kingdom Motivation

Three-phase SMA model with optimized fit for both strain and resistance 124
Max Hauber, Arif Kazi
Hochschule Aalen, Germany

Pneumatic cylinder speed control system using particle-excitation flow control valve 128
Daisueke Hirooka, Naomichi Furushiro, Tomomi Yamaguti
Kansai University, Japan

A steerable concentric push–pull suction device for single-port surgery 130
Finn Hoffmann, Bob Lathrop, Mouloud Ourak, Wouter Everaerts,
Emmanuel Vander Poorten, Paul Breedveld
Department of Mechanical Engineering, KU Leuven, Belgium
Department of Mechanical Engineering, TU Delft, The Netherlands
Department of Urology, University Hospitals Gasthuisberg, Katholieke Universiteit Leuven, Belgium

Lumped modelling of loss mechanisms in piezoelectric transducers 135
Jan Holterman, Bas Jansen, Henry Schmidt
VIRO, The Netherlands
ASML, The Netherlands

Piezoelectric ultrasonic mirror tip tilt stage 139
Jan Homberg, Alexej Wischnewski, Bülent Delibas
Physik Instrumente GmbH & Co. KG, Germany

Change in stress-strain-characteristics of MSM-alloys
in weak magnetic fields for a daptive interfaces.....142
Marco Hutter, Lukas Fuchs, Peter Schmid, Thomas Maier, Bernd Gundelsweiler
Institute of Design and Production in Precision Engineering, University of Stuttgart, Germany
Institute for Technical Design and Industrial Design, University of Stuttgart, Germany

Experimental setup for piezo relations validation.....147
Bas Jansen, Ivan Staykov, Paul Vrancken, Hans Butler, Siep Weiland
ASML, The Netherlands
TU/e, Eindhoven, The Netherlands,

Development of a highly dynamic and precise actuator
with magnetic weight compensation for 3D-wafer scanning.....151
Maik Kadias, Heiko Knoll, Matthias Böhle, Dr. Rolf Slatter
ITK Precisioning GmbH, Germany
ELSOMA GmbH, Germany

Experiencing Coupled Resonance Dynamics when Designing with Vibrotactile Actuators.....155
Prof. Dr. Thorsten A. Kerna, Dr. Mohammad Sadeghia, Dr. Ornella Tortoricia, Maximilian Beckera, Juliana Lüera, Ali Elnwegya,
Institute for Mechatronics in Mechanics, Hamburg University of Technology, Hamburg, Germany
ligeti center, Hamburg, Germany

Creep modeling and stability of PNZT shape memory piezoelectric actuators.....161
Jurrien Keulen, Mireny Ugalde Reygadas, Bayu Jayawardhana, Monica Acuautla Meneses
University of Groningen, The Netherlands

Reliability and drift behaviour of CNT-modified grippers for soft robotics applications.....165
Ivica Kolaric, Rolf Nothelfer-Richter, Takushi Sugino, Hirosato Monobe
Fraunhofer IPA, Germany
National Institute of Advanced Industrial Science and Technology (AIST), Japan

Theoretical and experimental investigations regarding small electric drive systems overload potentials in short-term operation 171
Ulrike Kurz, Andreas Wagener, Bernd Gundelsweiler
Institute of Design and Production in Precision Engineering, University of Stuttgart, Germany
Dr. Fritz Faulhaber GmbH & Co. KG, Germany

Multi-DOF steerable endoscope for robot-surgeon collaborative control 177
Robert Lathrop, Mouloud Ourak, Emmanuel Poorten
KU Leuven, Belgium

Finite Element Analysis of Asymmetric Inflatable Snapping Actuators 182
Xin Li, Edoardo Milana
Department of Microsystems Engineering - IMTEK, University of Freiburg, Freiburg, Germany

Dual-Chevron Optothermal Rotary Microactuator for High Force and Large Displacement Actuation 186
Yanze Li1, Alex J Thompson, Alfredo Fantetti, Belal Ahmad
Department of Surgery and Cancer, Imperial College London, United Kingdom
Department of Mechanical Engineering, Imperial College London, United Kingdom

Dual-Joint Cable-Driven Soft actuator for Miniaturized Flexible Endoscopy 190
Zijian Liu, Luigi Manfredi
University of Dundee, United Kingdom

Enhancing the reliability of piezoelectric actuators and motors under severe self-Heating, high-cycle operation, and harsh environmental conditions 194
Rasmus Lou-Møller, Iman Mehdipour, Charles Mangeot, Nicolas Bourgeot, Frank Claeyssen, Boris Laluc
CTS Denmark, Denmark, Cedrat Technologies, France

3D nano-printed optical MEMS with closed-loop control 199
Florian Lux, Elijah Ditchendorf, Çağlar Ataman
(University of Freiburg, Germany)

Magnetoelectric cantilever beam with reduced bending mitigates power nulls in Wireless Power Transfer systems 203
Hidelberto Macedo Zamudio, Pascal M. Weber, Tobias Gräf, Ulrike Wallrabe
University of Freiburg, IMTEK – Department of Microsystems Engineering, Laboratory for Microactuators, Germany

Compact piezo-driven inchworm rotary mechanism with high rotational accuracy for LISA Space mission 207
Narendra Mahavar, Shashwat Kushwaha, Dominiek Reynaerts
KU Leuven, Belgium, Member Flanders Make, Belgium

Piezoelectric transducer for high intensity reversible acoustic rotational field generation 213
Piotr Vasiljev, Dalius Mažeika, Andrius Čeponis, Regimantas Bareikis, Sergejus Borodinas, Vilnius Gediminas
Technical University, Lithuania
Vytautas Magnus University, Lithuania

Compact piezoelectrically driven inchworm motor with large forces and strokes using advanced control 217
Ulrich Mescheder, Sonja Müller, Jahangir Khosravi, Bahman Azarhoushang
Hochschule Furtwangen, Germany, Universität Freiburg, Germany

Design methodology for electromechanical functional interfaces..... 223
Tom Migliaccio, François Pigache, Thomas Huguet
Laplace, France

Dual-mode electrosurgical device for selective tissue perforation via electrically-induced bubbles and discharge..... 227
Shigeaki Miura, Yuudai Aokusa, Mayu Nakahigashi, Nobutoshi Ota, Yoko Yamanishi
Kyushu University, Japan

Optimizing laser-induced graphene microstructure to enhance ion diffusion and actuation performance in PI-LIG-Ppy ionic actuators..... 230
David Morales, Alejandro Vega, Sergio Gabriel Flores
(CIMAV, Mexico)

Non-contact micro-mechanical stimulation of Arabidopsis root cap using ultrasonic standing waves for mechanotransduction analysis..... 233
Keisuke Morishima, Koki Ogawa
The University of Osaka, Japan

Thermal Impact on the Dynamic Model of a Magnetorheological Elastomer: Analysis and Experiments..... 238
Paweł Orkisz, Janusz Goldasz, Bogdan Sapiński
AGH University of Science and Technology, Poland
Cracow University of Technology, Poland

Plasmid delivery to suspension cells through electromechanical poration induced by a microbubble generator 242
Nobutoshi Ota, Kei Tateishi, Shigeo Sugano, Niko Kimura, Shinya Sakuma, Yoko Yamanishi
Kyushu University, Japan
National Institute of Advanced Industrial Science and Technology, Japan
Tokyo University of Agriculture and Technology, Japan

Bistable Piezoelectric Energy harvester with embedded power management electronics for railway monitoring..... 245
Timoteo Payre, Boris Laluc, Nicolas Decroix, Quentin Demouron, Celestin Metral, Romane Anseaume, Guillaume Mansuy
CEDRAT TECHNOLOGIES S.A.S, France
USMB, France, VOSSLOH, France

Closed-loop cooperative control of dielectric elastomer actuator arrays 248
Alberto Priuli, Saverio Addario, Benjamin Zemlin, John Heppe, Gianluca Rizzello
Saarland University, Department of Systems Engineering, Saarbrücken, Germany
University of Applied Sciences, Department of Sensors and Thin Films, Saarbrücken, Germany.

Engineering liquid crystal elastomer fibers for the next generation of soft robotics: A comparative analysis of fabrication techniques 253
Manuel Reis Carneiro, Rafael Molter, Aníbal T. de Almeida, Mahmoud Tavakoli
Soft Machines Lab, Department of Mechanical Engineering, Carnegie Mellon University, Pittsburgh, USA
Institute of Systems and Robotics, Department of Electrical and Computer Engineering, University of Coimbra, Portugal;
Biomedical and Mobile Health Technology Lab, Department of Health Sciences and Technology, ETH Zürich, Switzerland

Surface-dominated drying and crystallization effects in micropumps 259
Martin Richter , Mohammadhossein Sheikhsarraf
Fraunhofer EMFT, Germany

Conceptual desi gn of a Tunable Magnet-based Reluctance Actuator 263
Endre Peder Ronaes, Andres Hunt, Ron van Ostayen, Hassan Hossein Nia
(Delft Univeristy of Technology, The Netherlands)

Design and characterization of a tactile multi-element dielectric elastomer actuator 266
Lukas Moritz Roth, Sebastian Gratz-Kelly, Daniel Bruch, Sophie Nalbach, Paul Motzki,
Saarland University, Germany
Center for Mechatronics and Automation Technology – ZeMA gGmbH, Germany

Design and control of motion stage driven by nonlinear reluctance actuator 272
Mohammad Saaideh, Natheer Alatawneh, Mohammad Al Janaideh
University of Guelph
Fraunhofer Institute for Applied Optics and Precision Engineering, Germany and University of Toronto

Displacement control for Piezo-based Deformable Mirrors with Unmodelled Hysteresis and Actuator Coupling 278
Mohammad Saaideh, Matthias Goy, Mohammad Al Janaideh
University of Guelph
Fraunhofer Institute for Applied Optics and Precision Engineering, Germany
Fraunhofer Institute for Applied Optics and Precision Engineering, Germany & University of Toronto

Integration of sensors and trajectory control for the autonomous navigation of 3D-printed miniature robots driven by piezoelectric actuators 284
Byron Ricardo Zapata Chancusig, Jaime Rolando Heredia Velastegui,
Víctor Ruiz-Díez and José Luis Sánchez-Rojas.
Mechatronic Department, Universidad Politécnica Salesiana, Ecuador.
Microsystems, Actuators and Sensors Group, INAMOL-Universidad de Castilla-La Mancha, Spain

Investigation of the influence of dynamic magnetic excitation during drag finishing using abrasive magnetorheological fluids 289
Fabian Sordon, Jürgen Maas
(Mechatronic Systems Lab, Technische Universität Berlin, Germany)

Amplified Piezo Actuators with embedded Eddy Current Sensor for cryo space De-SPIN mechanism 295
Olivia Stadler, Jocelyn Rebufa, Alexis Gierczak, Clément Cote, David Ferris, François Barillot,
Frank Claeyssen, Boris Laluc, Guillaume Mansuy
CEDRAT TECHNOLOGIES S.A.S, France

Engineered shape memory behavior in Nb-doped lead zirconate titanate piezoelectric actuators 299
M. Ugalde-Reygadas, M. Acuautla
Engineering and Technology Institute Groningen, University of Groningen, The Netherlands

SUPERPOSITION-BASED FORCE MODELING OF A MULTI-STABLE MAGNETIC LIFT ACTUATOR 303
Pascal M. Weber, Michael Olbrich, Yannik T. Rüde1, Christoph Ament, Ulrike Wallrabe
Laboratory for Microactuators, IMTEK – Department of Microsystems Engineering, University Freiburg, Germany
Chair of Control Engineering, Faculty of Applied Computer Science, University of Augsburg, Germany

Impact of Actuator Pretension and Heat Treatment on the Performance of Piezoelectric Micromembrane Pumps 305
Nora Weigel, Martin Wackerle, Daniel Anheuer, Gabriele Schrag, Martin Richter
Fraunhofer Research Institution for Microsystems and Solid-State Technologies EMFT, Munich, Germany, Technical University of Munich, Germany

Prototype of a camera focusing mechanism driven by a polyimide bimorph thin-film actuator 311
Daisuke Yamaguchi, Saki Takamura, Shuichi Wakimoto, Takefumi Kanda
(Okayama University, Japan)

Interlocking-based multistable actuators as fluidic memristors 313
Ayberk Yüksek, Mohsen Jafarpour, Edoardo Milana,2
Freiburg Center for Interactive Materials and Bioinspired Technologies, Germany
Department of Microsystems Engineering (IMTEK), University of Freiburg, Germany

Investigation of a pressure-driven dielectric elastomer multi-actuatorsystem 323
Bingzhi Wanga, Andreas Hubracht, Abdelkarim Masouda, Chen Jiaob, Ashwani Sharan Tripathib, Uwe Marschnerb, Andreas Richterb, E. F. Markus Vorrathb, and Jürgen Maasa
Mechatronic Systems Lab, Technische Universität Berlin, Germany
Institute of Semiconductors and Microsystems, Technische Universität Dresden, Germany

Battery-powered high-voltage electronics with a PCB-integrated transformer for driving dielectric elastomer actuators 325
Andreas Hubracht, Jürgen Maas
Mechatronic Systems Lab, Technical University Berlin, Germany